

Contents

Preface	v
Preface to <i>Introduction into the Theory of Uniform Approximation of Functions by Polynomials</i> by V. K. Dzyadyk	vii
Chapter 1. Chebyshev theory and its development	1
1. Chebyshev theorems	2
1.1. Existence of the element of the best approximation	2
1.2. Chebyshev alternation theorem	4
1.3. On the number of zeros of trigonometric polynomials	10
2. Chebyshev systems of functions	14
2.1. Definitions, examples	14
2.2. Basic properties of the Chebyshev systems	17
2.3. Chebyshev systems of real functions on an interval	20
2.4. Uniqueness of the best approximation by generalized polynomials	26
2.5. De la Vallée Poussin theorem	33
2.6. Snakes	35
2.7. Representation of positive polynomials	38
3. Chebyshev polynomials	45
4. On the best uniform approximation of continuous functions of complex variable	51
4.1. Kolmogorov theorem	52
4.2. Examples of application of Theorem 4.1	54
4.3. De-la-Vallée-Poussin-type theorem	57
4.4. Characteristic sets	58
5. Approximation of functions on sets of finitely many points	64
5.1. Best approximation of a system of linear equations	64
5.2. General case	73

6. Algorithms of construction of polynomials of the best approximation	79
7. Approximation of functions by polynomials with linear constraints imposed on their coefficients	86
Remarks to Chapter 1	106
Chapter 2. Weierstrass theorems	111
1. First Weierstrass theorem	112
2. Stone's theorem	117
2.1. Stone's theorem	117
2.2. Corollaries of Stone's theorem	123
3. Examples of polynomial kernels	124
3.1. Periodic kernels	125
3.2. Aperiodic kernels	151
4. Rational kernels and approximation of functions by rational polynomials	157
4.1. Newman theorem	157
4.2. Rational kernels	161
Remarks to Chapter 2	164
Chapter 3. On smoothness of functions	167
1. Modulus of continuity (of the first order)	168
1.1. Definition. Examples	168
1.2. Properties of the modulus of continuity	172
1.3. Concave majorant	176
2. Classes of functions defined by the first modulus of continuity	178
2.1. Hölder (Lipschitz) classes and spaces	178
2.2. Class $\text{Lip } 1$	179
2.3. Dini–Lipschitz condition	180
2.4. Classes $H[\varphi, J]$	181
3. Lagrange polynomials. Divided and finite differences	182
3.1. Lagrange polynomials	182
3.2. Divided differences	183
3.3. Finite differences	193

4. Moduli of continuity of higher order	197
4.1. Modulus of continuity of order k	197
4.2. Approach of Stechkin	201
4.3. Extremal function	203
4.4. Smoothing of a majorant	207
4.5. Is the relation $\omega_k(t; f) = O(\omega_m(t; f))$ true for $m > k$?	209
4.6. Gliding-hump method	211
4.7. Remarks	215
5. Marchaud inequality	215
5.1. Marchaud inequality	215
5.2. Some simple but important facts for the second modulus of continuity	219
5.3. Estimates for moduli of continuity of derivatives	222
5.4. On the exactness of Theorem 5.5	225
6. Whitney inequality	230
6.1. Whitney inequality	230
6.2. Sendov's conjecture	233
6.3. Corollaries of the Marchaud inequality and Whitney inequality	234
6.4. Estimate for a divided difference for arbitrary nodes	237
6.5. Proof of Theorem 6.4	240
7. Classes and spaces of functions defined by the k th modulus of continuity	245
7.1. Definitions	245
7.2. Relations between spaces of continuous functions	247
7.3. Space $H(\bar{\epsilon})$	252
7.4. Peetre K -functional	258
8. Hermite formula	259
8.1. Introduction	259
8.2. Hermite–Lagrange polynomial	261
8.3. Generalized divided difference	262
8.4. Convergence	265
8.5. Further generalization of the Whitney inequality	269
8.6. Existence of the derivative	269

9. <i>DT</i> -Moduli of smoothness	270
9.1. Introduction	270
9.2. Definition of <i>DT</i> -modulus of continuity (smoothness)	272
9.3. Properties of <i>DT</i> -modulus of continuity	277
9.4. Relationship between the <i>DT</i> -modulus of smoothness and the space B^r	282
10. DT_r -Modulus of smoothness	283
10.1. Spaces C_w^r	283
10.2. DT_r -modulus of smoothness	287
10.3. Properties of DT_r -modulus of continuity	291
10.4. Classes $B^r\bar{H}$ and $B_0^r\bar{H}$	294
10.5. Relationship between $\bar{\omega}_{k,r}(f^{(r)}; t)$ and $\omega_k(\tilde{f}^{(r)}; t)$	298
Chapter 4. Extension	299
1. Extension from intervals	300
2. Lemma on gluing	308
3. Interpolation problem	318
3.1. On the exactness of Theorem 3.6.3	319
3.2. On extension from “minimal” sets	325
3.3. Extension from an arbitrary set	325
4. Traces. Extension of complexes	326
Chapter 5. Direct theorems on the approximation of periodic functions	331
1. Singular integrals and Lebesgue constants	331
2. Direct theorems	333
Chapter 6. Inverse theorems on the approximation of periodic functions	345
1. Theorems on evaluation of the absolute value of the derivative of a polynomial	345
2. On the estimates of errors of application of the method of grids to the Chebyshev theory of approximation of functions	358
3. Inverse theorems	366

4. On the constructive characteristics of periodic functions of the Hölder and Zygmund classes	370
Remarks to Chapter 6	377
Chapter 7. Approximation by polynomials	379
1. Introduction	379
2. Inequality for the modulus of the derivative of an algebraic polynomial. Inverse theorem	383
3. Polynomial kernels. Direct theorem	392
4. On the application of the method of decomposition of unity to approximation of functions	407
5. Extreme functions	414
6. Shape-preserving approximation	418
7. On rational approximation	431
References	437
Subject index	479